



REV.NO.	REVISION DESCRIPTION	DRAWN / DATE	REVIEWED / DATE	APPROVED / DATE
	Previous versions omitted			
5	PTM line modified	KCH/20191206	JJS/20191206	KTJ/20191206
6	Number range dispys changed	KYJ/20241119	JJS/20241119	KTJ/20241119

$R_L$  = Resistance value(Power + Wire + Monitoring system)

$$R_L \leq \frac{V_s[V] - 9[V]}{I [mA]}$$

PROJECT NAME \_\_\_\_\_

SURFACE TEXTURE		-		PRODUCT NAME		SMART POSITIONER	
FINISH TREATMENT		-		MODEL		YT-2500, 2550	
MATERIAL		-		PROJECTION		3rd	
OTHERWISE NOTE		-		SCALE		-	
GENERAL TOLERANCE		-		QUANTITY		1	
				SHEET No.		1 / 1	

Rotork YTC Limited <small>GIMPO-SI, KOREA</small>		TITLE		YT-2500/2550 + HART + Analog Output WIRING DIAGRAM	
		DRAWING NO.		2500-06	
		REV.		6	