Volume Booster

YT-300 / 305 / 310 / 315 / 320 / 325 Series

SIL Safety Instruction.

Supplement to product manual

Rotork YTC Limited

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Table of contents

1 Introduction	3
1.1 Purpose of this document	3
1.2 Field of Application	
1.3 Required documentation	3
1.4 Further information	3
2 Acronyms and abbreviations	4
3 Relevant standards	5
4 Terms and definitions	5
5 Determining the Safety Integrity Level (SIL)	5
6 Safety-related system	7
7 Information for the safety function	8
8 Periodic checks	9
9 Safety engineering parameters	10
9.1 Prerequisites	10
9.2 Specific safety-related parameters	10
10 Glossary	
11 Certificate	

1 Introduction

1.1 Purpose of this document

This document contains information and safety instructions that the user will require when using the volume booster in safety-related systems.

This document is for system planners, constructors, service & maintenance engineers and personnel who will perform commissioning the device.

1.2 Field of Application

The application includes control valve with volume boosters boosting air flow up to SIL3 level in accordance with the safety engineering requirements of IEC61508. Volume boosters are suitable for SIL2 at HFT=0 and for SIL3 at HFT=1

In the event of a pneumatic power failure, the air supply to signal port and supply port will be exhaust, and the pressurized air in actuator chamber will be exhausted to atmosphere through exhaust hole of volume booster due to the movement of actuator's return spring. As a result, the position of stroke will be moved to the predefined safe end position (either OPEN or CLOSED).

1.3 Required documentation

This document only defines YT-300/305/310/315/320/325 volume booster's safety functions. This document only applies in conjunction with YT-300/305/310/315/320/325 Product Manual.

1.4 Further information

The contents of these instructions shall not become part of or modify any prior existing agreement, commitment or legal matter.

Any statements contained herein do not create new warranties or modify the existing warranty.

The content reflects the technical status at the time of printing.

YTC reserves the right to make technical changes in the course of further development.

2 Acronyms and abbreviations

Acronym	Full term in English	Description	
HFT	Hardware Fault Tolerance	Hardware fault tolerance:	
		Ability of a function unit (Hardware) to continue	
		executing a required function in the presence of	
		faults or deviations.	
MTBF	Mean Time Between	Average period between two failures	
	Failures		
MTTR	Mean Time To Repair	Average period between the occurrence of a fault	
		in a device or system and the repair	
PFD	Probability of Failure on	Probability of dangerous failures of a safety	
	Demand	function on demand	
PFDavg	Average Probability of	Average probability of dangerous failures of a	
	Failure on Demand	safety function on demand	
SIL	Safety Integrity Level	The international standard IEC 61508 defines four	
		discrete Safety Integrity Levels (SIL 1 to SIL 4). Each	
		level corresponds to a range of probability for	
		failure of a safety function. The higher the Safety	
		Integrity Level of the safety-related system, the	
		lower the probability that it will not execute the	
		required safety functions.	
SFF	Safe Failure Fraction	Proportion of safe failures:	
		Proportion of failure without the potential to bring	
		the safety-related system into a dangerous or non-	
		permissible functional status.	
FIT	Failure in Time	Frequency of failure	
		Number of faults within 10^9 hours	
TI	Test Interval	Testing interval of the protective function	
λsd	Failure rate for all safe	Overall rate for all safe detected failures.	
	detected failures		
λsu	Failure rate for all safe	Overall rate for all unsafe detected failures.	
	undetected failures		
λdd	Failure rate for all	Overall rate for all dangerous detected failures	
	dangerous detected		
	failures		
Лdu	Failure rate for all	Overall rate for all dangerous undetected failures	
	dangerous undetected		
	failures		

3 Relevant standards

Standard	English	German
IEC 61508, Part 1 to 7	Functional safety of electrical / electronic /	
	programmable electronic safety-related systems	
	(Target group: Manufacturers and Suppliers of	
	Devices).	

4 Terms and definitions

Terms	Explanation		
Dangerous failure	A failure that has the potential to place the safety-related system in a		
	dangerous state or render the system inoperative.		
Safety-related system	A safety-related system performs the safety functions that are required		
	to achieve or maintain a safe condition, e.g., in a plant.		
	Example: pressure meter, logics unit (e.g., limit signal generator) and		
	valve form a safety-related system.		
Safety function	A specified function that is performed by a safety-related system with		
	the goal, under consideration of a defined hazardous incident, of		
	achieving or maintaining a safe condition for the plant. Example: limit		
	pressure monitoring		

5 Defining the Safety Integrity Level (SIL)

The achievable Safety Integrity Level is defined by the following safety-related parameters:

- Average probability of hazardous failures for a safety function on demand (PFDavg)
- Hardware Fault Tolerance (HFT)
- Fraction of failures that do not have the potential to put the safety-related system in a hazardous or fail-to-function state (SFF)

The specific safety-related parameters for YT-300/305/310/315/320/325 volume boosters as part of a safety function are listed in the section "Safety-related parameters".

The following table shows the dependence of the safety Integrity Level (SIL) on the Average Probability of Failure on Demand (PFDavg).

The table applies the "low demand mode", i.e. the safety-related system is check at most once a year

Safety Integrity Level (SIL)	PFDavg (low demand mode)
4	$\geq 10^{-5}$ < 10^{-4}
3	$\geq 10^{-4}$ < 10^{-3}
2	$\geq 10^{-3}$ < 10^{-2}
1	$\geq 10^{-2} \dots < 10^{-1}$

6 Safety-related system

Sensor, logics unit and actuator (positioner, volume booter, pneumatic actuator and valve) form a safety-related system that performs a safety function.

The Average Probability of Failure on Demand (PFDavg) is usually divided between the sensor, logics unit and actuator sub-system.

Typical division of the Average Probability of Failure on Demand (PFDavg) into sub-system



Functional description

If the pneumatic power which is being supplied to the positioner and the volume booster is blocked, following safety function will be activated.

The pressurized air in actuator chamber will be exhausted to atmosphere through exhaust hole of volume booster due to the movement of actuator's return spring. As a result, the position of stroke will be moved to the predefined safe end position (either OPEN or CLOSED). 7 Information for the safety function

Important

Safety-related systems without a self-locking function must be monitored or set to an otherwise safe condition after performing the safety function within MTTR (8 hours).

The device lifecycle must be evaluated according to the specified MTBF.

8 Periodic checks

Safety checks

The Safety function for the entire safety loop must be checked regularly in accordance with IEC 61508.

The test intervals are determined when calculating the individual safety loops of a plant(PFDavg's).

On the YT-300/305/310/315/320/325 volume booster, the following specific checks should be carried out:

Connect the set value of 0 MPa.

- Check whether the valve moves to the appropriate safety position – "tight closing".

Functional checks

We recommend that the functioning of the volume booster is checked at regular intervals of one year.

Check at least the following:

- 1. Connect the set value of 0 MPa.
 - Check whether the valve moves to the appropriate end position.
 - Check the locally displayed internal, digitized values for the setpoint and position.
- 2. Connect the set value of the appropriate pneumatic pressure.
 - Check whether the valve moves to the appropriate end position.
 - Check the locally displayed internal, digitized values for the setpoint and position.

Repairs

When you send a defective device to the repair department, include information describing the error and, if possible, the cause.

Important

When ordering replacement devices always provide the lot number of the original device (on the name plate)

9 Safety engineering parameters

- 9.1 Prerequisites
 - The compressed air supply is free of oil, water and dust in accordance with DIN/ ISO 8573-1.
 - The repair period (MTTR) following a device fault is 8 hours.
 - The mean temperature over a longer period of time is 40 $^\circ\!\mathrm{C}$
 - The volume booster is used only in applications with low request rates (low demand mode).
- 9.2 Specific safety-related parameters

Important

The PFDav values provided in the table are valid for YT-300/305/310/315/320/325 volume boosters.

Туре	Category	Λdu	PFDavg
YT-300/305/	SIL2 at 1oo1(HFT=0)	6.90 x 10 ⁻⁸ /h	3.07 x 10 ⁻⁴ at 1001
310/315/			
320/325	SIL3 at 1002(HFT=1)		3.08 x 10 ⁻⁵ at 1002

10 Glossary

Dangerous failure

Failure with the potential to bring the safety-related system into a dangerous or non-functional status.

Safety function

Defined function executed by a safety-related system with the objective of achieving or maintaining a safe system status taking into account a defined dangerous occurrence. Example:

Limit pressure monitoring

Safety Integrity Level

Safety-related system

A safety-related system executes the safety functions that are required to achieve or maintain a safe status in a system.

It consists of a sensor, logic unit/control system and final controlling element. Example:

A safety-related system is made up of a pressure transmitter, a limit signal sensor and a control valve.

SIL

The international standard IEC 61508 defines four discrete Safety Integrity Level (SIL) from SIL 1 to SIL 4. Each level corresponds to the probability range for the failure of a safety function. The higher the SIL of the safety-related system, the higher probability that the required safety function will work.

11. Certificate

Certificate			
No.: 968/V 1235.00)/21		
Product tested	Air Volume Booster	Certificate holder	Rotork YTC Limited 81, Hwanggeum-ro 89 Beon-gil, Yangchon- eup Gimpo-si, Gyeonggi-do, 10048 South Korea
Type designation	YT-300, YT-305, YT-310, Y	T-315, YT-320, YT-	325
Codes and standards	IEC 61508 Parts 1-2 and 4-7	:2010	
Intended application	Safety Function: Close on Demand The volume boosters are suitable for use in a safety instrumented system		
	up to SIL 2 (low demand mode). Under consideration of the minimum required hardware fault tolerance $HFT = 1$ the volume boosters may be used in a redundant architecture up to SIL 3.		
Specific requirements	The instructions of the assoc Manual shall be considered.	iated Installation, O	perating and Safety
Summary of test results see	back side of this certificate.		
Valid until 2026-05-19			
The issue of this certificate is ba CERT FSP1 V1.0:2017 in its ac 2021-05-18. This certificate is v	sed upon an evaluation in accordance with the Certification Program ual version, whose results are documented in Report No. 968/V 1235.00/21 dated alid only for products, which are identical with the product tested.		
	TÜV Rheinland Industrie Bereich Automat Funktionale Siche	Service GmbH ion rheit	Wolf P
Köln, 2021-05-19	Certification Body Safety & Security for	65totrialion & Grid	Dipl. Ing. (FH) Wolf Rückwart

968/V 1235.00/21 - page 2



Holder: Rotork YTC Limited

81, Hwanggeum-ro 89 Beon-gil, Yangchon-eup Gimpo-si, Gyeonggi-do, 10048 South Korea

Product tested: Air Volume Booster YT-300, YT-305, YT-310, YT-315, YT-320, YT-325

Results of Assessment

Route of Assessment		2 _H / 1 _S
Type of Sub-system		Туре А
Mode of Operation		Low Demand Mode
Hardware Fault Tolerance	HFT	0
Systematic Capability		SC 3

Closing on Demand

Dangerous Failure Rate		λ _D	6.90 E-08 / h	69 FIT	
	Average Probability of Failure on Demand 1001	$PFD_{avg}(T_1)$	3.07 E-04	4	
	Average Probability of Failure on Demand 1002	$PFD_{avg}(T_1)$	3.08 E-0	5	
		1. (2) YEAR ONLY 1997 (2010)			

Assumptions for the calculations above: DC = 0 %, T₁ = 1 year, MRT = 72 h, β_{1oo2} = 10 %

Origin of failure rates

The stated failure rates for low demand are the result of an FMEDA with tailored failure rates for the design and manufacturing process.

Furthermore the results have been verified by field-feedback data.

Failure rates include failures that occur at a random point in time and are due to degradation mechanisms such as ageing.

The stated failure rates do not release the end-user from collecting and evaluating application-specific reliability data.

Periodic Tests and Maintenance

The given values require periodic tests and maintenance as described in the Safety Manual. The operator is responsible for the consideration of specific external conditions (e.g. ensuring of required quality of media, max. temperature, time of impact), and adequate test cycles.

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