

# RedMax ¼ turn actuators – size S

Electrical, explosion proof rotary actuators

3-pos. / 0...10 VDC / 4...20 mA control mode, with feedback, 24...240 VAC/DC, 95° angle of rotation

5/10 Nm, 15/30 Nm without and 5/10 Nm, 15 Nm with safety operation (spring return)

ATEX tested in acc. with directive 2014/34/EU for zone 2, 22

RedMax - ... - Y  
 RedMax - ... - YF  
 RedMax - ... - CTS  
 RedMax - ... - VAS

Subject to change!

## Compact. Easy installation. Universal. Cost effective. Safe.

| Type              | Torque  | Supply           | Motor running time             | Spring return | Control mode                  | Feedback               | Wiring diagram |
|-------------------|---|------------------|--------------------------------|---------------|-------------------------------|------------------------|----------------|
| RedMax- 5.10 - Y  | 5 / 10 Nm   | 24...240 V AC/DC | 7,5 / 15 / 30 / 60 / 120 s/90° | –             | 3-pos., 0...10 VDC, 4...20 mA | 0...10 V DC, 4...20 mA | SB 5.0 – 5.3   |
| RedMax-15.30 - Y  | 15 / 30 Nm  | 24...240 V AC/DC | 7,5 / 15 / 30 / 60 / 120 s/90° | –             | 3-pos., 0...10 VDC, 4...20 mA | 0...10 V DC, 4...20 mA | SB 5.0 – 5.3   |
| RedMax- 5.10 - YF | 5 / 10 Nm   | 24...240 V AC/DC | 7,5 / 15 / 30 / 60 / 120 s/90° | 3 or 10 s/90° | 3-pos., 0...10 VDC, 4...20 mA | 0...10 V DC, 4...20 mA | SB 5.0 – 5.3   |
| RedMax- 15 - YF   | 15 Nm   | 24...240 V AC/DC | 7,5 / 15 / 30 / 60 / 120 s/90° | 3 or 10 s/90° | 3-pos., 0...10 VDC, 4...20 mA | 0...10 V DC, 4...20 mA | SB 5.0 – 5.3   |
| RedMax- ... - CTS | Types as above with aluminium housing and seawater resistant coating (cable glands brass nickel-plated) |                  |                                |               |                               |                        |                |
| RedMax- ... - VAS | Types as above with stainless steel housing for aggressive ambient (cable glands brass nickel-plated)   |                  |                                |               |                               |                        |                |

### Product views and applications

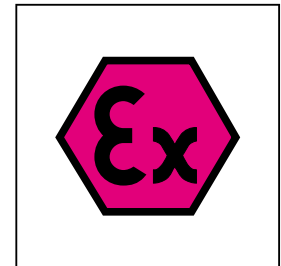
Safety damper



Ball valve



Throttle valve



### Description

The RedMax actuators are a revolution for safety, control and shut-off dampers, VAV systems, ball valves, throttle valves and other motorized applications for HVAC systems in chemical, pharmaceutical, industrial and offshore/onshore plants, for use in Ex-areas zone 2 (gas) and zone 22 (dust).

Highest protection class (ATEX) and IP66 protection, small dimensions, only 3,5 kg weight, universal functions and technical data, an integrated heater and an optional stainless steel housing guarantee safe operation even under difficult environmental conditions. High quality brushless motors guarantee long life.

All actuators are programmable and adjustable on site. Special tools or equipment are not required. Motor running times and torques as well as spring return times, according to the actuator type, are selectable or adjustable on site. The integrated universal power supply is self adaptable to input voltages in the range of 24...240 VAC/DC. Furthermore it is possible to perform control signal inverting and compulsion control by certain connections. The actuators are 100 % overload protected and self locking.

...Max-...-YF actuators are equipped with spring return fail safe function. Standard shaft connection is a double square direct coupling with 12 x 12 mm.

Different accessories are available to adapt auxiliary switches, terminal boxes or adaptations for ball valves and throttle valves and other armatures.

### Highlights

- ▶ For all types of gases, mists, vapours and dusts in zones 2 and 22
- ▶ Universal supply unit from 24...240 VAC/DC
- ▶ 5 different motor running times 7,5–15–30–60–120 s/90°, adjustable on site
- ▶ 2 different spring return running times ~ 3–10 s/90°, selectable on site
- ▶ 3-pos. and 0...10 VDC, 4...20 mA control mode with or without spring return function
- ▶ Feedback signals 0...10 VDC and 4...20 mA
- ▶ Reverse function
- ▶ 5–10–15–30 Nm actuators in the same housing size
- ▶ 100 % overload protected and self locking
- ▶ Compact design and small dimension (L x W x H = 210 x 95 x 80 mm)
- ▶ Direct coupling to the damper shaft with double square connection 12 x 12 mm
- ▶ 95° angle of rotation inclusive 5° pretension
- ▶ Robust aluminium housing (optional with seawater resistant coating) or in stainless steel
- ▶ IP66 protection
- ▶ Simple manual override included + preparation for comfortable manual override
- ▶ Gear made of stainless steel and sinter metal
- ▶ Weight only ~ 3,5 kg
- ▶ Integrated heater for ambient temperatures down to -40 °C
- ▶ Integrated safety temperature sensor
- ▶ Integrated equipment for manual adjustment (push button, lamp, switch)
- ▶ Preparation for adaptable and adjustable auxiliary switches type ...Switch



| Technical data                       | RedMax- 5.10 -Y   | RedMax- 15.30 -Y                  | RedMax- 5.10 -YF  | RedMax- 15 -YF                   |
|--------------------------------------|---|-----------------------------------|---|----------------------------------|
| Torque motor (min.)                  | 5 / 10 Nm selectable on site  | 15 / 30 Nm selectable on site     | 5 / 10 Nm selectable on site                                | 15 Nm                            |
| Torque spring (F)                    | –   | –                                 | min. 10 Nm  | min. 15 Nm                       |
| Torque blockade                      | In blockade and end positions torques are higher than above specified torques for motor and spring.   |                                   |   |                                  |
| Dimensioning of external load        | Upon spring return the external load should be max. 80 % of torque spring (F).  |                                   |   |                                  |
| Supply voltage / frequency           | 24...240 VAC/DC $\pm$ 10 %, self adaptable, frequency 50...60 Hz $\pm$ 20 %   |                                   |   |                                  |
| Power consumption                    | max. starting currents see ① Extra information (in acc. with voltage, $I_{start} \gg I_{rated}$ ), approx. 5 W holding power, approx. 16 W for heater   |                                   |   |                                  |
| Protection class                     | Class I (grounded)  |                                   |   |                                  |
| Angle of rotation and indication     | 95° incl. $\sim$ 5° pretension, mechanical value indication   |                                   |   |                                  |
| Working direction                    | Selectable by left/right mounting to the damper/valve shaft   |                                   |   |                                  |
| Motor running times                  | 7,5 / 15 / 30 / 60 / 120 s/90° selectable on site   |                                   |   |                                  |
| Motor                                | Brushless DC motor  |                                   |   |                                  |
| Control mode Y                       | 3-pos., 0...10 VDC, 4...20 mA in acc. with wiring, selectable on site. Galvanic separation between supply and Y-signal  |                                   |   |                                  |
| Feedback signal U                    | 0...10 VDC, 4...20 mA in acc. with wiring, selectable on site, both signals are available at the same time  |                                   |   |                                  |
| Resistance of Y and U signals        | <b>Input signal:</b> $U_U$ 0...10 VDC at 10 k $\Omega$ , $Y_1$ 4...20 mA at 100 $\Omega$ . <b>Feedback signal:</b> $U_U$ 0...10 VDC at 2.000... $\infty$ $\Omega$ , $U_1$ 4...20 mA at 0...800 $\Omega$ |                                   |   |                                  |
| Reverse function                     | Bridge between wiring 3 and 4 (signal wise) gets a reverse function of Y and U  |                                   |   |                                  |
| Compulsion control                   | In modulation mode an On-off compulsion control can be performed by external connection /wiring independently from the modulating signal  |                                   |   |                                  |
| Adjustment of Y and U                | In case of external mechanical limitation of the angle of rotation, it is possible to perform an adjustment drive started by pushing the button (T)   |                                   |   |                                  |
| Spring return (F)                    | –   | –                                 | spring return upon voltage interruption                     |                                  |
| Spring return response time          | –   | –                                 | up to 1 sec. after voltage interruption                     |                                  |
| Spring return running time (F)       | –   | –                                 | $\sim$ 3 or 10 s/90° selectable on site                     |                                  |
| 3 sec. mode – spring return          | –   | –                                 | $\sim$ 3 to 4 s/90° angle of rotation acc. to external load |                                  |
| Safety operations at 10 sec. (F)     | –   | –                                 | min. 10,000 acc. to construction of damper and ambient      |                                  |
| at 3 sec. (F)                        | –   | –                                 | min. 1,000 acc. to construction of damper and ambient       |                                  |
| Axle of the actuator                 | Double square 12 $\times$ 12 mm, direct coupling, 100 % overload protected and self locking up to 15 Nm   |                                   |   |                                  |
| Electrical connection                | 2 cables $\sim$ 1 m each, wire cross section 0.5 mm <sup>2</sup> , equipotential bonding 4 mm <sup>2</sup> .<br>Connections in hazardous areas require a terminal box!                                  |                                   |   |                                  |
| Diameter of cable                    | $\sim$ $\varnothing$ 7.1 + 7.4 mm   | $\sim$ $\varnothing$ 7.1 + 7.4 mm | $\sim$ $\varnothing$ 7.4 mm each                            | $\sim$ $\varnothing$ 7.4 mm each |
| Cable gland                          | M16 $\times$ 1.5 mm   |                                   |   |                                  |
| Manual override                      | Use delivered socket wrench, max. 4 Nm  |                                   |   |                                  |
| Heater                               | Integrated, controlled heater for ambient temperature down to $-40$ °C  |                                   |   |                                  |
| Housing material                     | Aluminium die-cast housing, coated. Optional with seawater resistant coating (...-CTS) or stainless steel housing,<br>№ 1.4581 / UNS-J92900 / similar AISI 316Nb (...-VAS)                              |                                   |   |                                  |
| Dimensions (L $\times$ W $\times$ H) | 210 $\times$ 95 $\times$ 80 mm, for diagrams see ① Extra information  |                                   |   |                                  |
| Weight                               | $\sim$ 3,5 kg aluminium housing, stainless steel $\sim$ 7 kg  |                                   |   |                                  |
| Ambients                             | Storage temperature $-40...+70$ °C, working temperature $-40...+40$ °C at T6 and $-40...+50$ °C at T5   |                                   |   |                                  |
| Humidity                             | 0...90 % rH, non condensing   |                                   |   |                                  |
| Operating 7,5 sec. motor run time    | at 24 V: S3 – 50 % ED intermittent mode (ED = duty cycle)   |                                   |   |                                  |
| $\geq$ 15 sec. motor run time        | at 15 / 30 / 60 / 120 s 100 % of ED is permitted  |                                   |   |                                  |
| Accuracy electrically                | $\sim$ 100 steps  |                                   |   |                                  |
| Self adjustment                      | Before initial operation you need to start the self adjustment mode for „gentle blockade“ and adjustment of rotation angle  |                                   |   |                                  |
| Wiring diagrams                      | SB 5.0 / 5.1 / 5.2 / 5.3  |                                   |   |                                  |
| Scope of delivery                    | Actuator, 4 screws M4 $\times$ 100 mm, 4 nuts M4, Allen key for simple manual override  |                                   |   |                                  |
| Parameter at delivery                | 5 Nm, 30 s/90°  | 15 Nm, 30 s/90°                   | 5 Nm, 30 s/90°  | 15 Nm, 30 s/90°                  |

### Approbations

|                       |  |
|-----------------------|--|
| ATEX Directive        | 2014/34/EU                                   |
| ATEX Conformity       | EPS 18 ATEX 1 216 X                          |
| IECEX Conformity      | IECEX EPS 18.0107X                           |
| Marking Gases         | II 3 (3) G Ex db [ic Gc] IIC T6, T5 Gc       |
| Types ...-CTS         | II 3 (3) G Ex db [ic Gc] IIB T6, T5 Gc       |
| Marking Dusts         | II 3 (3) D Ex tc [ic Dc] IIC T80°C, T95°C Dc |
| CE Marking            | CE 0158                                      |
| EMC Directive         | 2014/30/EU                                   |
| Low Voltage Directive | 2014/35/EU                                   |
| Enclosure Protection  | IP66 in acc. with EN 60529                   |

### Special solutions and accessories

|               |   |
|---------------|---|
| ...-CTS       | Types in aluminium housing with seawater resistant coating, parts nickel-plated |
| ...-VAS       | Types in stainless steel housing, parts nickel-plated                           |
| RedBox-Y/S... | Terminal boxes for zone 2, 22   |
| MKK-S         | Mounting bracket for boxes type ...Box-... directly on actuator                 |
| RedSwitch     | 2 external aux. switches, adjustable for zone 2, 22                             |
| HV-S...       | Comfortable manual override for...Max actuators size S                          |
| KB-S          | Clamp for damper shafts $\varnothing$ 10...20 mm and $\square$ 10...16 mm       |
| AR-12-xx      | Reduction part for 12 mm square connection to 11, 10, 9 or 8 mm shafts          |
| Kit-S8        | Cable glands nickel-plated  |
| Adaptions     | for dampers and valves on request   |



Electrical connection

All actuators are equipped with a universal supply unit working at a voltage range from 24...240 VAC/DC. The supply unit is self adjusting to the connected voltage! The safety operation of the spring return function works if the supply voltage is cut.

For electrical connection inside hazardous areas a terminal box is required (e.g. RedBox). An over-current protection fuse < 10 A has to be provided by installer. Note: the initial current is appr. 2 A for 1 second.

**Modulating / 3-pos. – with / without spring return SB 5.0**

**Self adjustment:**  
To adjust the signal input/output to the angle of rotation of the damper/valve the button (T) must be pushed for a minimum of 3 sec.

**Selection of running time for spring return:**  
Spring return in ~ 10 s = Standard wiring  
Spring return in ~ 3 s = Additional wiring on terminal 5

**Reverse function:**  
Bridge 3–4 reverses the input and output signals

**Function and enforcement control of switch a and b in modulating mode:**

- a closed – **Forced-ON (OFF)** in acc. to left/right mounting of actuator
- b closed – **Forced-OFF (ON)** in acc. to left/right mounting of actuator

**Modulating – with / without spring return (no enforcement) SB 5.1**

**Self adjustment:**  
To adjust the signal input/output to the angle of rotation of the damper/valve the button (T) must be pushed for a minimum of 3 sec.

**Selection of running time for spring return:**  
Spring return in ~ 10 s = Standard wiring  
Spring return in ~ 3 s = Additional wiring on terminal 5

**Reverse function:**  
Bridge 3–4 reverses the input and output signals

**Modulating – with / without spring return (no feedback) SB 5.2**

**Self adjustment:**  
To adjust the signal input/output to the angle of rotation of the damper/valve the button (T) must be pushed for a minimum of 3 sec.

**Selection of running time for spring return:**  
Spring return in ~ 10 s = Standard wiring  
Spring return in ~ 3 s = Additional wiring on terminal 5

**Reverse function:**  
Bridge 3–4 reverses the input signals

**3-pos. – with / without spring return + feedback SB 5.3**

**Self adjustment:**  
To adjust the signal input/output to the angle of rotation of the damper/valve the button (T) must be pushed for a minimum of 3 sec.

**Attention!**  
When changing 3-position mode into modulating regard function, see page 4 – Parametrisation D)

**Selection of running time for spring return:**  
Spring return in ~ 10 s = Standard wiring  
Spring return in ~ 3 s = Additional wiring on terminal 5

**Reverse function:**  
Bridge 3–4 reverses the output signals

**3-pos. control mode:**

- a closed, b open – **ON (OFF)** in acc. to left/right mounting of actuator
- b closed, a open – **OFF (ON)** in acc. to left/right mounting of actuator

**Installation**

Ex area – zone 2, 22

Safe area

Y: 0...10 V / 4...20 mA  
U: 0...10 V / 4...20 mA

supply\*  
24...240 VAC/DC ± 10 %

\* electrical wiring see diagrams

**Important information for installation and operation**

**A. Installation, commissioning, maintenance**

All national and international standards, rules and regulations for hazardous Ex-areas must be complied with. Certified apparatus must be installed in accordance with manufacturer instructions. If the equipment is used in a manner not specified by the manufacturer, the safety protection provided by the equipment may be impaired. For electrical installations design, selection and erection, EN/IEC 60079-14 can be used. For electrical connection an Ex-e terminal box is required (e.g. RedBox-...).

**Attention:** If the actuator is put out of operation all Ex rules and regulations must be applied. You have to cut the supply voltage before opening the terminal box! The cables of the actuator must be installed in a fixed position and protected against mechanical and thermal damage. Connect potential earth. Avoid temperature transfer from armature to actuator! Close all openings with min. IP66. For outdoor installation a protective weather shield against sun, rain and snow should be applied to the actuator as well as a constant supply at terminal 1 and 2 for the integrated heater. During commissioning apply a self adjustment drive.

continue next page



### Important information for installation and operation

Actuators are maintenance free. An annual inspection is recommended. For electrical installations inspection and maintenance, EN/IEC 60079-17 can be used. Ex-actuators must not be opened by the customer.

#### B. Manual override

Manual override only if supply voltage is cut. Use delivered socket wrench with slow motions, usage can be tight. **Attention:** Releasing or letting go the Allen key too fast at manual operating actuators with spring return causes risk of injury!

#### C. Shaft connection, selection of running time

Actuators are equipped with a direct coupling double square shaft connection of 12 × 12 mm. For round shafts adaptors/clamping connection (accessories, e.g. KB-S) are available. The housing of the actuator is axially symmetrically built to select Open-close direction of the spring return function by left-right mounting. Using the 10-position switch different motor running times and spring return running times can be selected on site in acc. to the actuator type.

#### D. 3-position control mode

...Max actuators are in the best way suitable for the 3-pos. operation. To protect such elements as gears and mounting elements against harmful influences like minimum pulse time, ...Max actuators are protected via internal electronics. It ignores impulses < 0.5 s, the cyclic duration must be min. 0.5 s. At changing direction the pause is 1 s.

#### E. Spring return

Spring return function works only if the supply voltage for terminal 1 or 2 is cut. In the event of an electrical interruption, the spring returns to its end position even if supply voltage is available again during return function. Thereafter operation will continue.

#### F. Operation at ambient temperatures below -20 °C

All actuators are equipped with a regulated integrated heating device designed for employments down to -40 °C ambient temperature. The heater will be supplied automatically by connecting the constant voltage supply on the clamps 1 and 2.

1. After mounting the actuator must be immediately electrically connected.
2. The heater switches on automatically when actuator reaches internally -20 °C. It heats up the actuator to a proper working temperature, then heater switches off automatically. Actuator will not run during heating process.
3. The adjustment options are only ensured after this heating up period.

#### G. Excess temperatures

In acc. to the ATEX rules and regulations Ex actuators must be protected against excess temperature. The internal thermostat works as a maximum limiter and, in the event of failure at incorrect temperatures, shuts off the actuator irreversibly. An upstream connected temperature sensor stops the actuator before reaching its max. temperature. This safety feature is reversible, after cooling down the actuator is completely functional again. In this case the failure must be eliminated immediately on site!

#### H. Synchron mode

Do not connect several actuators to one shaft or link mechanically together.

#### I. Mechanical protection

Actuators must be operated with a minimum external load. After installing the actuator to the damper/armature a self adjustment drive has to be performed in order to protect the damper/armature against mechanical overload. During operation the actuator reduces briefly its speed (motor power) before reaching the end position for a "gentle" blockade/stop.

#### J. Intrinsically safe circuits

The supply of the push button (adjustment drive), the 10-position switch (adjustment of torque and running time) and the LED indicator is performed intrinsically safe!

### ⓘ Extra information (see additional data sheet)

Additional technical information, dimensions, installation instruction, illustration and failure indication

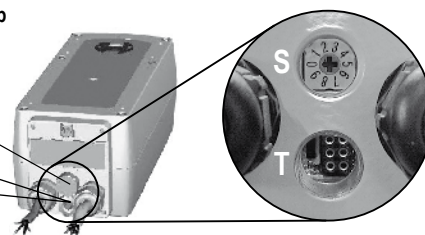
### Parameters, adjustments and failure indication

#### Switch – Push button – Lamp for adjustment (behind the blanking plug)

10-position switch (S)

Push button (T)

3-colour LED



#### Parameter selection

Example:

RedMax-15.30-Y

**Requested parameter:**

Torque 30 Nm  
Motor running time 30 s/90°

| Type                    | Torques              |              |
|-------------------------|----------------------|--------------|
| RedMax- 5.10-Y ▶        | 5 Nm                 | 10 Nm        |
| <b>RedMax-15.30-Y ▶</b> | <b>15 Nm</b>         | <b>30 Nm</b> |
| RedMax- 5.10-YF ▶       | 5 Nm                 | 10 Nm        |
| RedMax- 15-YF ▶         | 15 Nm                |              |
|                         | ▼                    | ▼            |
| Running times           | Position of switch S |              |
| 7,5 s/90° ▶             | 00                   | 05           |
| 15 s/90° ▶              | 01                   | 06           |
| <b>30 s/90° ▶</b>       | <b>02</b>            | <b>07</b>    |
| 60 s/90° ▶              | 03                   | 08           |
| 120 s/90° ▶             | 04                   | 09           |

**Result:**

Switch position **07**

### Functions, adjustments and parameters

#### A) Self adjustment of angle of rotation

Turn switch (S) to position 02 (low torque) or 07 (high torque). Press button (T) for a minimum of 3 seconds. The actuator drives to both end positions and detects the blocking positions. The LED flashes GREEN during adjustment.

The adjustment takes about 60 seconds (30 sec. "On", 30 sec. "Off").

#### B) Selecting motor running time and torque

Adjust parameters only if actuator is in idle state or without applied potential.

Turn switch (S) to the position required for the intended operation acc. to table above. The selected parameters will be carried out at the actuator's next operation.

#### C) Selecting spring return time

Spring return time is selected by wiring.

#### D) Changing modulating operation to 3-pos. operation with feedback

Modulating mode: The LED lights GREEN, potential applied.

Press button (T) briefly 3 times:

- each for at least 0.2 seconds
- altogether within max. 5 seconds

The LED changes from steady GREEN to steady YELLOW\*.

#### E) Changing 3-pos. operation with feedback to modulating operation

3-pos. mode: The LED lights YELLOW\*, potential applied.

Press button (T) briefly 3 times.

The LED changes from steady YELLOW\* to steady GREEN.

#### F) Additional information for control in 3-pos. operation with feedback

a closed, b open = direction I      a and b closed = motor doesn't work

b closed, a open = direction II      a and b open = motor doesn't work

The rotation direction (I and II) depends on left/right mounting of the actuator to the damper. To reverse the rotation direction (by motor) exchange the electrical wiring of terminal 3 and 4.

In 3-pos. operation with feedback the Y-inputs are without function.

#### G) Inverting <=> Reverting

Bridging signal wires 3–4 (cable B) inverts the function of input signals Y and feedback signals U.

\* Note: "YELLOW" may vary from yellowish to orange.



During commissioning apply a self adjustment drive.  
Regard duty cycle at motor running times!  
Never use spring return actuators without external load.