



ExRun Valve actuators with continuous control

ExRun - ... - Y ExRun - ... - CTS

Subject to change!

Electrical, explosion proof linear actuators - 500 N to 10,000 N 24...240 VAC/DC, 5...60 mm adjustable stroke ATEX tested in acc. with directive 2014/34/EU for zone 1, 2, 21, 22

Compact. Easy installation. Universal. Cost effective. Safe.

Туре	Force	Supply	Motor running time	or running time Control mode		Wiring diagram
ExRun- 5.10 - Y	0,5 kN / 1,0 kN	24240 VAC/DC	2/3/6/9/12s/mm	010 VDC, 420 mA	010 VDC, 420 mA	SB 4.0
ExRun- 25.50 - Y	2,5 kN / 5,0 kN	24240 VAC/DC	2/3/6/9/12s/mm	010 VDC, 420 mA	010 VDC, 420 mA	SB 4.0
ExRun- 75.100- Y	7,5 kN / 10,0 kN	24240 VAC/DC	4/6/9/12/15 s/mm	010 VDC, 420 mA	010 VDC, 420 mA	SB 4.0
ExRun CTS	Types as above with aluminium housing and seawater resistant coating (exterior parts in stainless steel, cable glands brass nickel-plated)					

Product views and applications

...Run



Side view



Back view with terminal box ...Run mounted on valve





Compact body



Description

ExRun valve actuators are the new generation of electrical, explosion proof adjustment and control valves and other motorized applications for HVAC systems in chemical, pharmaceutical, industrial and offshore/onshore plants, for use in Ex-areas zone 1, 2 (gas) and zone 21, 22 (dust).

Highest protection class and IP66 protection, compact dimensions, little weight, universal functions and technical data and an integrated heater guarantee safe operation even under difficult environmental conditions. High quality brushless motors guarantee long life.

All actuators are programmable and adjustable on site. Special tools or equipment are not required. Motor running times and forces, according to the actuator type, are selectable or adjustable on site. The integrated universal power supply is self adaptable to input voltages in the range of 24...240 VAC/DC. The actuators are 100 % overload protected and self locking.

The modular concept offers the possibility to mount adjustable end switches for signalization.

Highlights

- ▶ For all type of gas, mists, vapours and dust for use in zone 1, 2, 21 and 22
- ► Universal supply unit from 24...240 VAC/DC
- ► Integrated junction box
- ► Motor running times 2-3-4-6-9-12-15 s/mm, acc. to type
- ► Continuous control, feedback signals 0...10 VDC and 4...20 mA
- ▶ Reverse function
- ► Forces 500-1000-2500-5000-7500-10000 N, acc. to type
- ► Feedback gear unit, adjustable in steps 10 / 20 / 30 / 60 mm
- ► Mechanical stroke limitation, 5...60 mm stroke adjustable
- ► 100 % overload protected and self locking
- ► Compact design and small dimensions
- ► Robust aluminium housing (optional with seawater resistant coating)
- ► IP66 protection
- ► Manual override included + preparation for comfortable manual override
- ► Weight ~ 7 kg
- ► Integral safety temperature sensor
- Status indication by LED



Special option ... -CTS



Force (nominal) 0.5 / 1,0 kN selectable 2,5 / 5,0 kN selectable 7,5 / 10 kN selectable Blocking force in end position* - 1,2 / 1,8 kN - 4 / 7,5 kN - 10 / 12,5 kN Supply voltage / frequency 24240 VAC/DC, ± 10 %, self adaptable, frequency 5060 Hz ± 20 % Power consumption max. starting currents see ⊕ Extra information (in acc. with voltage, I start >> I rested), 2 A innush current Protection class Class I (grounded) - 10 kW (motor is not running at this moment), turns on automatically at low ambient temperatures Stroke 560 mm (adjustable) 2 / 3 / 6 / 9 / 12 s / mm 2 / 3 / 6 / 9 / 12 s / mm 4 / 6 / 9 / 12 / 15 s / mm Motor running times (selectable) 2 / 3 / 6 / 9 / 12 s / mm 2 / 3 / 6 / 9 / 12 s / mm 4 / 6 / 9 / 12 / 15 s / mm Motor Gottorlo mode Y 010 VPC, 4 20 mA in acc. with wiring, selectable on site. Galvanic separation between supply and Y-signal 4 / 6 / 9 / 12 / 15 s / mm Resistance of Y and U signals Input signal: Y 010 VPC, 4 20 mA in acc. with wiring, selectable on site. Galvanic separation between supply and Y-signal Reverse function Bridge between terminals 3 – 4 (signal line) elefted to site, both signals are available at the same time Reverse function Bridge between terminals 3 – 4 (signal line) elefted to a reverse f	Technical data	ExRun- 5.10 -Y	ExRun- 25.50 -Y	ExRun- 75.100 -Y				
Supply vortage / frequency 24240 VAC/DC, ± 10 %, self adaptable, frequency 5060 Hz ± 20 % Power consumption max. starting currents see ⊕ Extra information (in acc. with voltage, I start ≫ I related), 2 A inrush current Relater consumption ~16 W (motor is not running at this moment), turns on automatically at low ambient temperatures Stroke 560 mm (adjustable) Motor running times (selectable) 2/3 / 6 / 9 / 12 s/mm 2 / 3 / 6 / 9 / 12 s/mm 4 / 6 / 9 / 12 f s/mm Control mode Y 010 VDC, 420 mA in acc. with wiring, selectable on site. Galvanic separation between supply and Y-signal Feedback signal U 010 VDC, 420 mA in acc. with wiring, selectable on site, both signals are available at the same time Reverse function Bridge between terminals 3 – 4 (signal line) effects a reverse function of input and output signals (Y and U) Compulsion control In modulation mode an On-off compulsion control can be performed by external connection/wiring independently from the modulating signal Adjustment of Y und U In case of external mechanical limitation of operating displacement, it is possible to perform an adjustment drive started by bouching the button box incl. terminals 0,144 mm² Cable gland M20 × 1,5 mm, Il/2GD Ex-e approved, cable diameter Ø 613 mm Manual override Change from motor to hand mode with red turn-switch on the side, use Allen key's top side, max. 5 Nm	Force (nominal)	0,5 / 1,0 kN selectable	2,5 / 5,0 kN selectable	7,5 / 10 kN selectable				
Power consumption max. starting currents see ⊕ Extra information (in acc. with voltage, I start >> I rated), 2 A inrush current Protection class Class I (grounded) Heater consumption 2.6 W (motor is not running at this moment), turns on automatically at low ambient temperatures Stroke 550 mm (adjustable) Motor running times (selectable) 2 / 3 / 6 / 9 / 12 s/mm 2 / 3 / 6 / 9 / 12 s/mm 4 / 6 / 9 / 12 s/mm 4 / 6 / 9 / 12 s/mm Control mode Y 010 VDC, 420 mA in acc. with wiring, selectable on site, both signals evaluable at the same time Reedback signal U 010 VDC, 420 mA in acc. with wiring, selectable on site, both signals are available at the same time Resistance of Y and U signals Input signal: V ₁₀ 010 VDC at 10 kD, Y ₁ 420 mA at 100 Ω Feedback signal U ₁ 010 VDC at 10 kD, Y ₁ 420 mA at 1.00 Ω Reverse function 3 indige between terminals 34 (signal line) effects a reverse function of input and output signals (Y and U) Compulsion control In modulation mode an On-off compulsion control can be performed by external connection/wiring independently from the modulating signal limitation of operating displacement, it is possible to perform an adjustment drive started by bucching the button of personal displacement, it is possible to perform an adjustment drive started by touching the button of personal personal connection / wiring independently from the modulating signal line is developed. <tr< td=""><td>Blocking force in end position *</td><td>~ 1,2 / 1,8 kN</td><td>~ 4 / 7,5 kN</td><td colspan="3">~ 10 / 12,5 kN</td></tr<>	Blocking force in end position *	~ 1,2 / 1,8 kN	~ 4 / 7,5 kN	~ 10 / 12,5 kN				
Protection class Class I (grounded) Heater consumption ~ 16 W (motor is not running at this moment), turns on automatically at low ambient temperatures Stroke 560 mm (adjustable) Motor running times (selectable) 2/3 / 6 / 9 / 12 s/mm 2 / 3 / 6 / 9 / 12 s/mm 4 / 6 / 9 / 12 s/mm 4 / 6 / 9 / 12 s/mm Motor Brushless DC motor Control mode Y 010 VDC, 420 mA in acc. with wiring, selectable on site. Galvanic separation between supply and Y-signal Feedback signal U 010 VDC, 420 mA in acc. with wiring, selectable on site, both signals are available at the same time Resistance of Y and U signals Input signal: Yu 010 VDC at 1.000∞ Ω, U₁ 420 mA at 10.00 Ω Reverse function Bridge between terminals 3 -4 (signal line) effects a reverse function of input and output signals (Y and U) Compulsion control In modulation mode an On-off compulsion control can be performed by external connection of input and output signals (Y and U) Adjustment of Y und U In case of external mechanical limitation of operating displacement, it is possible to perform an adjustment drive started by touching the button of the side, use Allen key's top side, max. 5 Nm Cable gland M20 × 1,5 mm, Il2GD Ex-e approved, cable diameter Ø 613 mm Manual override Change from motor to hand mode with red turn-switch on the side,	Supply voltage / frequency	24240 VAC/DC, ± 10 %, self adaptable, frequency 5060 Hz ± 20 %						
Heater consumption	Power consumption							
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Motor running times (selectable) 2/3/6/9/12 s/mm 2/3/6/9/12 s/mm 4/6/9/12/15 s/mm Motor Brushless DC motor Control mode Y 010 VDC, 420 mA in acc. with wiring, selectable on site. Galvanic separation between supply and Y-signal Feedback signal U 010 VDC, 420 mA in acc. with wiring, selectable on site, both signals are available at the same time Resistance of Y and U signals Input signal: Y₁010 VDC at 1.00 x20, 1/420 mA at 0800 Ω Reverse function Bridge between terminals 3 –4 (signal line) effects a reverse function of input and output signals (Y and U) Compulsion control In modulation mode an On-off compulsion control can be performed by external connection/wiring independently from the modulating signal Adjustment of Y und U Ex- ejunction box incl. terminals 0,144 mm² Electrical connection Ex- ejunction box incl. terminals 0,144 mm² Cable gland M20 x 1,5 mm, II/2GD Ex-e approved, cable diameter Ø 613 mm Manual override Aluminium die-cast housing, coated. Optional with seawater resistant coating (CTS) Dimensions (L × W × H) - 208 x 115 x 254 mm (types ≤ 5 kN), - 208 x 115 x 298 mm (types ≥ 7,5 kN), for diagrams se ⊕ Extra information Weight - 7 kg (standard version without adaption) Ambient temperature -30 °C -30	Heater consumption	~ 16 W (motor is not running at this moment), turns on automatically at low ambient temperatures						
Motor Brushless DC motor Control mode Y 010 VDC, 420 mA in acc. with wiring, selectable on site. Galvanic separation between supply and Y-signal Feedback signal U 010 VDC, 420 mA in acc. with wiring, selectable on site, both signals are available at the same time Resistance of Y and U signals Input signal: V _U 010 VDC at 10 kΩ, Y ₁ 420 mA at 10.00 Ω Feedback signal: V _U 010 VDC at 10 kΩ, Y ₁ 420 mA at 0800 Ω Reverse function Bridge between terminals 3-4 (signal line) effects a reverse function of input and output signals (Y and U) Compulsion control In modulation mode an On-off compulsion control can be performed by external connection/wiring independently from the modulating signal Adjustment of Y und U In case of external mechanical limitation of operating displacement, it is possible to perform an adjustment drive started by touching the button Electrical connection Ex-e junction box incl. terminals 0,144 mm² 613 mm Manual override Change from motor to hand mode with red turn-switch on the side, use Allen key's top side, max. 5 Nm Housing material Aluminium die-cast housing, coated. Optional with seawater resistant coating (CTS) Dimensions (L × W × H) ~ 208 × 115 × 254 mm (types ≤ 5 kN), ~ 208 × 115 × 298 mm (types ≥ 7,5 kN), for diagrams see ①Extra information Weight ~ 7 kg (standard version without ad	Stroke	560 mm (adjustable)						
Control mode Y 010 VDC, 420 mA in acc. with wiring, selectable on site. Galvanic separation between supply and Y-signal Feedback signal U 010 VDC, 420 mA in acc. with wiring, selectable on site, both signals are available at the same time Resistance of Y and U signals Input signal: Y _U 010 VDC at 10 kΩ, Y₁ 420 mA at 1.00 Ω Feedback signal: U _U 010 VDC at 1.000∞ Ω, U₁ 420 mA at 0800 Ω Reverse function Bridge between terminals 3 – 4 (signal line) effects a reverse function of input and output signals (Y and U) In modulation mode an On-off compulsion control can be performed by external connection/wiring independently from the modulating signal Adjustment of Y und U In case of external mechanical limitation of operating displacement, it is possible to perform an adjustment drive started by touching the button Ete-teical connection Ex-e junction box incl. terminals 0,144 mm² Cable gland M20 × 1,5 mm, II2GD Ex-e approved, cable diameter Ø 613 mm Manual override Change from motor to hand mode with red turn-switch on the side, use Allen key's top side, max. 5 Nm Housing material Aluminium die-cast housing, coated. Optional with seawater resistant coating (CTS) Dimensions (L × W × H) 208 × 115 × 254 mm (types ≤ 5 kN), ~ 208 × 115 × 298 mm (types ≥ 7,5 kN), for diagrams see ④ Extra information Weight 7 kg (standard version without adaption) Ambient temperature −30 °C Humidity 090 % rH, non condensing Operation mode 33 −50 % ED intermittent mode (ED = duty cycle), max. 300 operating cycles / h Accuracy electrically 4 1 mm stroke (hysteresis) Accuracy electrically 200 steps acc. to stroke adjustment "Gear belt adjustment" (page 4) Wiring diagrams SB 4.0 For adjusting control and feedback signal U _V / U _{mA} acc. to stroke setting please note page 4	Motor running times (selectable)	2/3/6/9/12 s/mm	2/3/6/9/12 s/mm	4/6/9/12/15 s/mm				
Feedback signal U 010 VDC, 420 mA in acc. with wirring, selectable on site, both signals are available at the same time Resistance of Y and U signals Input signal: Y _U 010 VDC at 10 kΩ, Y ₁ 420 mA at 1.00 Ω Feedback signal: U _U 010 VDC at 1.000∞ Ω, U ₁ 420 mA at 0800 Ω Reverse function Bridge between terminals 3–4 (signal line) effects a reverse function of input and output signals (Y and U) Compulsion control In modulation mode an On-off compulsion control can be performed by external connection/wiring independently from the modulating signal Adjustment of Y und U In case of external mechanical limitation of operating displacement, it is possible to perform an adjustment drive started by touching the button Electrical connection Ex-e junction box incl. terminals 0,144 mm² Cable gland M20 × 1,5 mm, II2GD Ex-e approved, cable diameter Ø 613 mm Manual override Change from motor to hand mode with red turn-switch on the side, use Allen key's top side, max. 5 Nm Housing material Aluminium die-cast housing, coated. Optional with seawater resistant coating (CTS) Dimensions (L × W × H) ~ 208 × 115 × 254 mm (types ≤ 5 kN), ~ 208 × 115 × 298 mm (types ≥ 7,5 kN), for diagrams see ① Extra information Weight ~ 7 kg (standard version without adaption) Ambient temperature ~30 °C ~30~20 °C: reduced forces approx. 60 % of rated value, e.g.	Motor	Brushless DC motor						
Resistance of Y and U signals Input signal: Y _U 010 VDC at 1.00 kΩ, Y ₁ 420 mA at 1.00 Ω Reverse function Bridge between terminals 3-4 (signal line) effects a reverse function of input and output signals (Y and U) Compulsion control In modulation mode an On-off compulsion control can be performed by external connection/wiring independently from the modulating signal Adjustment of Y und U In case of external mechanical limitation of operating displacement, it is possible to perform an adjustment drive started by touching the button Electrical connection Ex-e junction box incl. terminals 0,144 mm² Cable gland M20 × 1,5 mm, II2GD Ex-e approved, cable diameter Ø 613 mm Manual override Change from motor to hand mode with red turn-switch on the side, use Allen key's top side, max. 5 Nm Housing material Aluminium die-cast housing, coated. Optional with seawater resistant coating (CTS) Dimensions (L × W × H) ~ 208 × 115 × 254 mm (types ≤ 5 kN), ~ 208 × 115 × 298 mm (types ≥ 7,5 kN), for diagrams see ⊕Extra information Weight ~ 7 kg (standard version without adaption) Ambient temperature ~30 °C Storage temperature ~40+70 °C, working temperature ~20+40 °C at T6 and ~20+50 °C at T5 Ambient temperature ~30 °C ~3020 °C: reduced forces approx. 60 % of rated value, e.g. 5 kN ≤ 3 kN (max.). Avoid icing! Humidity 090 % rH, non condensing Operation mode <	Control mode Y	010 VDC, 420 mA in acc. with w	riring, selectable on site. Galvanic separation be	etween supply and Y-signal				
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Compulsion control In modulation mode an On-off compulsion control can be performed by external connection/wiring independently from the modulating signal Adjustment of Y und U Adjustment of Y und U In case of external mechanical limitation of operating displacement, it is possible to perform an adjustment drive started by touching the button Electrical connection Ex-e junction box incl. terminals 0,144 mm² Cable gland M20 × 1,5 mm, II2GD Ex-e approved, cable diameter Ø 613 mm Manual override Change from motor to hand mode with red turn-switch on the side, use Allen key's top side, max. 5 Nm Housing material Aluminium die-cast housing, coated. Optional with seawater resistant coating (CTS) Dimensions (L × W × H) ~ 208 × 115 × 254 mm (types ≤ 5 kN), ~ 208 × 115 × 298 mm (types ≥ 7,5 kN), for diagrams see ⊕ Extra information Weight ~ 7 kg (standard version without adaption) Ambients Storage temperature −40+70 °C, working temperature −20+40 °C at T6 and −20+50 °C at T5 Ambient temperature −30 °C −30−20 °C: reduced forces approx. 60 % of rated value, e.g. 5 kN ≜ 3 kN (max.). Avoid icing! Humidity 090 % rH, non condensing Operation mode S3 − 50 % ED intermittent mode (ED = duty cycle), max. 300 operating cycles / h Accuracy mechanically < 1 mm stroke (hysteresis)		Feedback signal: U _U 010 VDC at	1.000∞ Ω , U _I 420 mA at 0800 Ω					
Adjustment of Y und U In case of external mechanical limitation of operating displacement, it is possible to perform an adjustment drive started by touching the button Electrical connection Ex-e junction box incl. terminals 0,144 mm² Cable gland M20 × 1,5 mm, Il2GD Ex-e approved, cable diameter Ø 613 mm Manual override Change from motor to hand mode with red turn-switch on the side, use Allen key's top side, max. 5 Nm Housing material Aluminium die-cast housing, coated. Optional with seawater resistant coating (CTS) Dimensions (L × W × H) ~ 208 × 115 × 254 mm (types ≤ 5 kN), ~ 208 × 115 × 298 mm (types ≥ 7,5 kN), for diagrams see ①Extra information Weight ~ 7 kg (standard version without adaption) Ambients Storage temperature ~40+70 °C, working temperature ~20+40 °C at T6 and ~20+50 °C at T5 Ambient temperature ~30 °C ~3020 °C: reduced forces approx. 60 % of rated value, e.g. 5 kN ≜ 3 kN (max.). Avoid icing! Humidity 090 % rH, non condensing Operation mode S3 ~ 50 % ED intermittent mode (ED = duty cycle), max. 300 operating cycles / h Accuracy mechanically < 1 mm stroke (hysteresis)	Reverse function							
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Cable gland M20 × 1,5 mm, Il2GD Ex-e approved, cable diameter Ø 613 mm Manual override Change from motor to hand mode with red turn-switch on the side, use Allen key's top side, max. 5 Nm Housing material Aluminium die-cast housing, coated. Optional with seawater resistant coating (CTS) Dimensions (L × W × H) ~ 208 × 115 × 254 mm (types ≤ 5 kN), ~ 208 × 115 × 298 mm (types ≥ 7,5 kN), for diagrams see ① Extra information Weight ~ 7 kg (standard version without adaption) Ambients Storage temperature ~40+70 °C, working temperature ~20+40 °C at T6 and ~20+50 °C at T5 Ambient temperature ~30 °C ~3020 °C: reduced forces approx. 60 % of rated value, e.g. 5 kN ≙ 3 kN (max.). Avoid icing! Humidity 090 % rH, non condensing Operation mode S3 ~ 50 % ED intermittent mode (ED = duty cycle), max. 300 operating cycles / h Accuracy mechanically < 1 mm stroke (hysteresis)	Adjustment of Y und U							
Manual overrideChange from motor to hand mode with red turn-switch on the side, use Allen key's top side, max. 5 NmHousing materialAluminium die-cast housing, coated. Optional with seawater resistant coating (CTS)Dimensions (L × W × H)~ 208 × 115 × 254 mm (types ≤ 5 kN), ~ 208 × 115 × 298 mm (types ≥ 7,5 kN), for diagrams see ①Extra informationWeight~ 7 kg (standard version without adaption)AmbientsStorage temperature −40+70 °C, working temperature −20+40 °C at T6 and −20+50 °C at T5Ambient temperature −30 °C−30−20 °C: reduced forces approx. 60 % of rated value, e.g. 5 kN \triangleq 3 kN (max.). Avoid icing!Humidity090 % rH, non condensingOperation modeS3 − 50 % ED intermittent mode (ED = duty cycle), max. 300 operating cycles / hAccuracy mechanically< 1 mm stroke (hysteresis)Accuracy electrically~ 200 steps acc. to stroke adjustment "Gear belt adjustment" (page 4)Wiring diagramsSB 4.0For adjusting control and feedback signal U_V / U_{mA} acc. to stroke setting please note page 4Scope of deliveryActuator with integrated junction box, Allen key for manual override	Electrical connection	Ex-e junction box incl. terminals 0,144 mm ²						
Housing material Aluminium die-cast housing, coated. Optional with seawater resistant coating (CTS) Dimensions (L × W × H) ~ 208 × 115 × 254 mm (types ≤ 5 kN), ~ 208 × 115 × 298 mm (types ≥ 7,5 kN), for diagrams see ① Extra information Weight ~ 7 kg (standard version without adaption) Ambients Storage temperature −40+70 °C, working temperature −20+40 °C at T6 and −20+50 °C at T5 Ambient temperature −30 °C −30−20 °C: reduced forces approx. 60 % of rated value, e.g. 5 kN ≜ 3 kN (max.). Avoid icing! Humidity 090 % rH, non condensing Operation mode S3 − 50 % ED intermittent mode (ED = duty cycle), max. 300 operating cycles / h Accuracy mechanically < 1 mm stroke (hysteresis)	Cable gland	M20 × 1,5 mm, II2GD Ex-e approved, cable diameter Ø 613 mm						
Dimensions (L × W × H) ~ 208 × 115 × 254 mm (types ≤ 5 kN), ~ 208 × 115 × 298 mm (types ≥ 7,5 kN), for diagrams see ① Extra information Weight ~ 7 kg (standard version without adaption) Ambients Storage temperature ~40+70 °C, working temperature ~20+40 °C at T6 and ~20+50 °C at T5 Ambient temperature ~30 °C ~3020 °C: reduced forces approx. 60 % of rated value, e.g. 5 kN ≜ 3 kN (max.). Avoid icing! Humidity 090 % rH, non condensing Operation mode \$3 - 50 % ED intermittent mode (ED = duty cycle), max. 300 operating cycles / h Accuracy mechanically < 1 mm stroke (hysteresis)	Manual override	Change from motor to hand mode with red turn-switch on the side, use Allen key's top side, max. 5 Nm						
Weight ~ 7 kg (standard version without adaption) Ambients Storage temperature -40+70 °C, working temperature -20+40 °C at T6 and -20+50 °C at T5 Ambient temperature -30 °C -3020 °C: reduced forces approx. 60 % of rated value, e.g. 5 kN ≜ 3 kN (max.). Avoid icing! Humidity 090 % rH, non condensing Operation mode S3 – 50 % ED intermittent mode (ED = duty cycle), max. 300 operating cycles / h Accuracy mechanically < 1 mm stroke (hysteresis)	Housing material	Aluminium die-cast housing, coated. Optional with seawater resistant coating (CTS)						
Ambients Storage temperature $-40+70$ °C, working temperature $-20+40$ °C at T6 and $-20+50$ °C at T5 Ambient temperature -30 °C -3020 °C: reduced forces approx. 60 % of rated value, e.g. $5 \text{ kN} \triangleq 3 \text{ kN}$ (max.). Avoid icing! Humidity 090 % rH, non condensing Operation mode $S3 - 50$ % ED intermittent mode (ED = duty cycle), max. 300 operating cycles / h Accuracy mechanically $< 1 \text{ mm}$ stroke (hysteresis) Accuracy electrically $\sim 200 \text{ steps}$ acc. to stroke adjustment "Gear belt adjustment" (page 4) Wiring diagrams $SB 4.0$ For adjusting control and feedback signal U_V / U_{mA} acc. to stroke setting please note page 4 Scope of delivery Actuator with integrated junction box, Allen key for manual override	Dimensions (L × W × H)							
Ambient temperature -30 °C -3020 °C: reduced forces approx. 60 % of rated value, e.g. 5 kN ≜ 3 kN (max.). Avoid icing! Humidity 090 % rH, non condensing Operation mode S3 – 50 % ED intermittent mode (ED = duty cycle), max. 300 operating cycles / h Accuracy mechanically < 1 mm stroke (hysteresis)	Weight							
Humidity 090 % rH, non condensing Operation mode S3 – 50 % ED intermittent mode (ED = duty cycle), max. 300 operating cycles / h Accuracy mechanically < 1 mm stroke (hysteresis)	Ambients							
Operation mode S3 – 50 % ED intermittent mode (ED = duty cycle), max. 300 operating cycles / h Accuracy mechanically < 1 mm stroke (hysteresis) Accuracy electrically ~ 200 steps acc. to stroke adjustment "Gear belt adjustment" (page 4) Wiring diagrams SB 4.0 For adjusting control and feedback signal U _V / U _{mA} acc. to stroke setting please note page 4 Scope of delivery Actuator with integrated junction box, Allen key for manual override	Ambient temperature −30 °C							
Accuracy mechanically Accuracy electrically Wiring diagrams Seperof delivery Actuator with integrated junction box, Allen key for manual override Accuracy electrically Control and feedback signal U _V / U _{mA} acc. to stroke setting please note page 4 Actuator with integrated junction box, Allen key for manual override	Humidity	090 % rH, non condensing						
Accuracy electrically ~ 200 steps acc. to stroke adjustment "Gear belt adjustment" (page 4) Wiring diagrams Sep 4.0 For adjusting control and feedback signal U _V / U _{mA} acc. to stroke setting please note page 4 Scope of delivery Actuator with integrated junction box, Allen key for manual override	Operation mode	S3 – 50 % ED intermittent mode (ED = duty cycle), max. 300 operating cycles / h						
Wiring diagrams SB 4.0 For adjusting control and feedback signal U _V / U _{mA} acc. to stroke setting please note page 4 Scope of delivery Actuator with integrated junction box, Allen key for manual override	Accuracy mechanically							
Scope of delivery Actuator with integrated junction box, Allen key for manual override	Accuracy electrically							
	Wiring diagrams							
Parameter at delivery 500 N, 6 s/mm 2,5 kN, 6 s/mm 7,5 kN, 9 s/mm	Scope of delivery							
	Parameter at delivery	500 N, 6 s/mm	2,5 kN, 6 s/mm	7,5 kN, 9 s/mm				

 $^{^{\}star}$ Uncertainty of measurement \pm 10 %. Note also the chapter on dimensioning!

Approbations					
ATEX directive	2014/34/EU				
EC type-approved	EPS 19 ATEX 1 077				
IECEx certified	IECEx EPS 19.0039				
Approval for gas	II 2 (2) G Ex db eb [ib Gb] IIC T6, T5 Gb				
TypesCTS	II 2 (2) G Ex db eb [ib Gb] IIB T6, T5 Gb				
Approval for dust	II 2 (2) D Ex tb [ib Db] IIIC T80°C, T95°C Db				
CE identification	CE № 0158				
EMC directive	2014/30/EU				
Low voltage directive	2014/35/EU				
Enclosure protection	IP66 in acc. with EN 60529				

Special solutions and accessories					
CTS	Types in aluminium housing with seawater resistant coating,				
	parts nickel-plated				
ExSwitch-R-L External linear aux. switches, 2 separately adjustable contacts, for					
	mounting onRun's spindle in zone 1, 2, 21, 22				
ExBox/SW	Ex-e terminal box for aux. switches Switch-R-L				
MKK-S	Mounting bracket, V2A, for terminal boxesBox directly on actuator				
HV-R	Retrofit manual override forRun actuators				
GMB-1	Rubber bellow, 60 mm				
WS-R	Weather shield in stainless steel				
Adaptions	For fittings and manufacturers on request				
ExRun-5.10-	Y-S1: at loss of control signal the rod stops and remains in current position				
ExRunS3	\leq 5 kN: Ambient temp. up to +60 °C (T4), 110240 VAC/DC, 25 % ED				

Special option

... -CTS

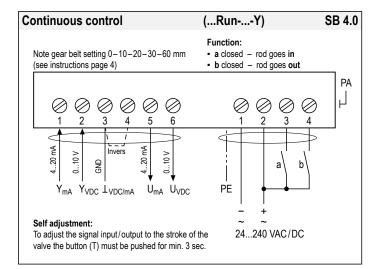


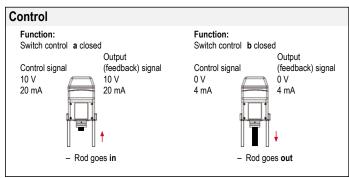
Electrical connection

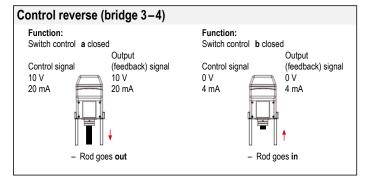
All actuators are equipped with a universal supply unit working at a voltage range from 24...240 VAC/DC. The supply unit is self adjusting to the connected voltage! Device must be fuse protected max. 5 AT.

Note current consumption acc. to running time and applied voltage (min. 2 A).

Integrated junction box Switch off the power Open cover of junction box 3. Put cable through cable gland into junction box Strip wires approx. 7 mm 5. Connect wires acc. to wiring diagram and type. Note: Wrong wiring expires guarantee Connect protection earth PE Fix wires, screw terminals Close cable entries tighten (IP66) 8. 9. Close cover junction box (regard gasket) analog in Supply analog out (3-6)IN/OUT control (3-4)







⚠ Attention **⚠**

At initial operation a self adjustment has to be executed.



Parameter selection

	Example: ExRun-25.50		Туре			Forces			Forces	
			ExRun-	5.10-Y	▶	500 N	1.000 N			
			ExRun-	-25.50-Y	▶	2.500 N	5.000 N			
	Requested par	ameter:	ExRun-	75.100-	Y►				7.500 N	10.000 N
	Force	5.000 N				•	•		\blacksquare	▼
	Running time	6 s/mm	Runnin	g times	F	Position of	f switch S	Running times	Position	of switch
			2	s/mm	▶	00	05	4 s/mm ▶	00	05
	Result:	_	3	s/mm	▶	01	06	6 s/mm ►	01	06
	Switch position 07		6	s/mm	▶	02	07	9 s/mm ▶	02	07
			9	s/mm	▶	03	80	12 s/mm ►	03	08
			12	s/mm	▶	04	09	15 s/mm ▶	04	09

Functions, adjustments and parameters

A) Self adjustment of stroke:

Push button (T) for minimum 3 seconds. The actuator will drive into both end positions to be adjusted. LED indicates GREEN.

Adjustment drive can be applied in any switch (S) position.

B) Selection of running time and force:

Put switch (S) into the correct selected position in acc. to above table. The selected parameter will work at next operation of the actuator. Adjustment can be done even without supply voltage. If supply voltage is available turn switch only if actuator is not running.

C) Force control:

a closed, b open = rod goes in b closed, a open = rod goes out

a and b closed = motor doesn't work, no function a and b opened = motor doesn't work, no function

Dimensioning

Force in blocking position after adjustment drive

The force in the end positions could be much more than the nominal force. Generally the valve is to check together with actuator and construed accordingly. Note the values in the "Technical Data".

Force during travel

The force during travel could be much more than the nominal force.

Self adjustment

To protect the valve/armature and the actuator in the end positions a self adjustment has to be performed before each commissioning or after any changes. Regard the gear belt adjustment according to the stroke!

ExRun-S-Y_e

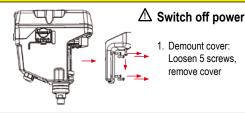


Special option

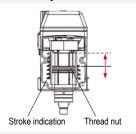
... -CTS



Stroke and gear belt adjustment

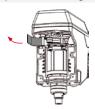


Stroke adjustment



Adjust/limitate stroke:
 Stroke can be adjusted by thread nut from min. 5 mm to 60 mm.

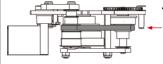
Open feedback gear's cover bracket



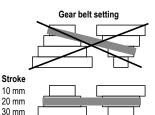
 Open cover bracket of feedback gear, thereby gear belt's tension is removed – not till then slide belt by hand to the right setting acc. to stroke. Do not use any tools.

Due to repeated movements of the red bar the setting of the gear belt gear can be changed. The position is corrected by closing the cover and starting a re-adjustment drive

Gear belt adjustment (for feedback signal U)



 Position gear belt acc. to set stroke. Do not use any sharp tools, manual operation only. Mind positioning. Set acc. to stroke.

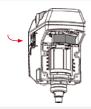


Feedback signal

By gear belt setting the feedback signal 0...10 V / 4...20 mA is adjusted to stroke. Example:

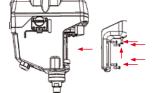
For stroke of 26 mm follows gear belt setting to position 30 mm. Start adjustment drive by pushing button (T) for 3 s. Thereby the feedback signal is setting stroke automatically to 26 mm (see also above "2. Stroke adjustment").

Close cover bracket of feedback gear



Note right position of gear belt! Close bracket, thereby the gear belt is automatically tensioned.

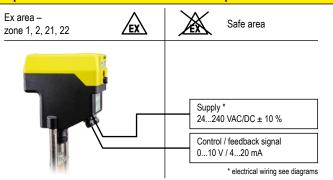
Remount cover



6. Note: cover gasket must be fit in the groove while mounting! Tighten 5 screws

Switch on power

Important information for installation and operation



- All national and international standards, rules and regulations for hazardous Ex-areas must be complied.
- Certified apparatus must be installed in accordance with manufacturer instructions. If the
 equipment is used in a manner not specified by the manufacturer, the safety protection
 provided by the equipment may be impaired.
- For electrical installations design, selection and erection, EN/IEC 60079-14 can be used.
- Supply cables must be installed in a fixed position and protected against mechanical damage
- For electrical connection use the integrated junction box
- Do not open the cover when circuits are live
- Connect potential earth
- Avoid temperature transfer from valve to actuator (note ambient temperature T_a!)
- Close all openings with min. IP66
- Flameproof enclosure is protected against mechanical damages acc. to EN 60079-ff
- For outdoor installation a protective weather shield against sun, rain and snow should be applied
- Actuators are maintenance free, an annual function test is recommended
- Clean only with damp cloth, avoid dust accumulation
- For electrical installations inspection and maintenance, EN/IEC 60079-17 can be used.

(i) Extra information (see additional data sheet)

Additional technical information, dimensions, installation instruction, illustration and failure indication

Manual override

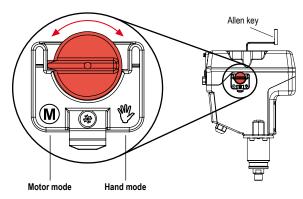


Attention



Turn hand feed crank slowly! When approaching the end positions overturning is possible and could damage the valve or actuator.

- 1. Actuator must be in stop position
- 2. Turn red switch to change from motor to hand mode
- 3. Turn to required stroke with Allen key (top side):
 - clockwise = rod out
 - counterclockwise = rod in
- 4. Upon completion turn back to motor mode



When operating the manual override in case of failure it is possible that the gear decouples. It can be seen that the selector switch is turned on "motor", but when controlled the actuator does not execute any stroke movement.

The blockade is resolved by simultaneously rotating the motor-hand switch and turning the Allen key in the hexagon shaft. The gear engages.

ExRun-S-Y_e 04 – 3-Jul-201

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